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RECOMMENDED FOR NEW DESIGNS***

SP8716/8/9

520MHz LOW CURRENT TWO-MODULUS DIVIDERS

SP8716 ÷ 40/41, SP8718 ÷ 64/65, SP8719 ÷ 80/81 are 50mW programmable dividers with a maximum specified operating frequency of 520MHz over the temperature range -40 °C to + 85 °C.

The signal (clock) inputs are biased internally and require to be capacitor coupled. The output stage is of an unusual low power design featuring dynamic pull-up, and optimised for driving CMOS. The 0 to 1 output edge should be used to give the best loop delay performance.

FEATURES

- DC to 520MHz Operation
- -40°C to +85°C Temperature Range
- Control Inputs and Outputs are CMOS Compatible

QUICK REFERENCE DATA

- Supply Voltage 5.0V ± 0.25V
- Supply Current 10.5mA typ.

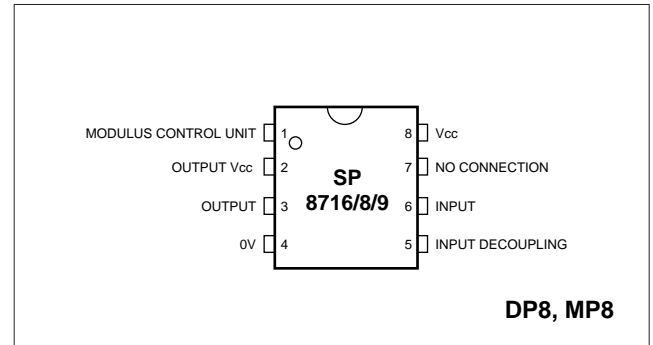


Figure : 1 Pin connections - top view

ABSOLUTE MAXIMUM RATINGS

Supply voltage pin 2 or 8):	8V
Storage temperature range:	-55°C to +150°C
Max. Junction temperature:	+175°C
Max. clock I/P voltage:	2.5V p-p

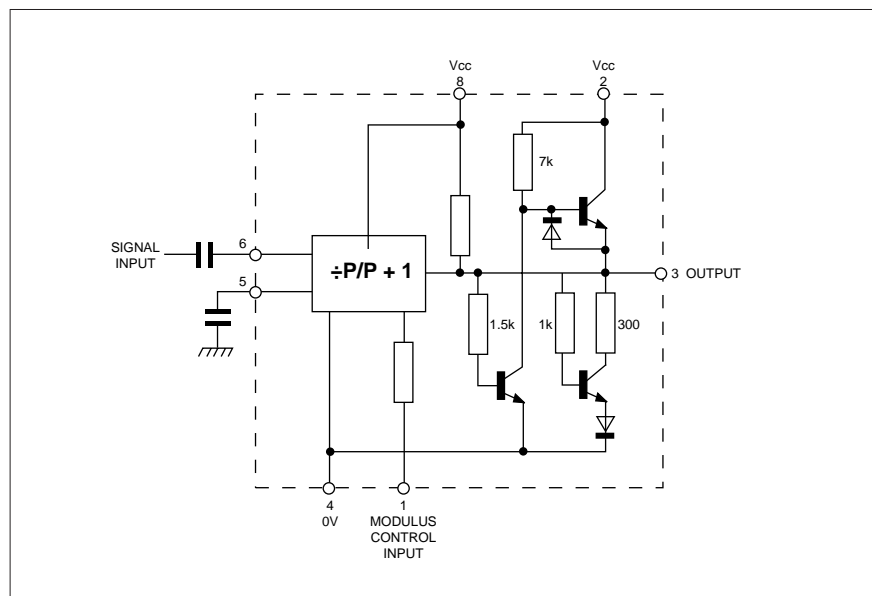


Figure 2 : Functional diagram

ELECTRICAL CHARACTERISTICS

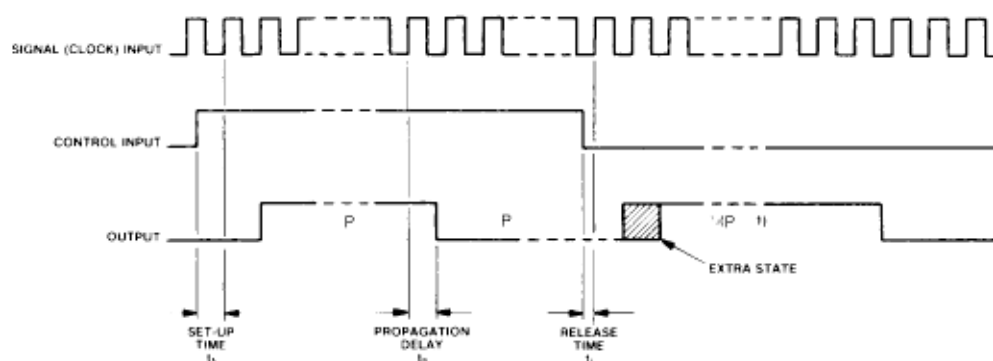
Test conditions (unless otherwise stated):]

Supply voltage: $V_{CC} = +4/95$ to $5.45V$, Temperature: $T_{amb} = -40^{\circ}C$ to $+85^{\circ}C$

Characteristics	Symbol	Value		Units	Conditions	Notes
		Min.	Max.			
Max. frequency	f_{max}	520		MHz	Input 100-280mV p-p	1
Min. frequency (sinewave input)	f_{min}		30	MHz	Input 400-800mV p-p	2
Power supply current	I_{CC}		11.9	mA	$C_L = 3pF$; pins 2, 8 linked	1
Output high voltage	V_{OH}	$(V_{CC} - 1.2)$		V	$I_L = -0.2mA$	1
Output low voltage	V_{OL}		1	V	$I_L = 0.2mA$	1
Control input high voltage	V_{INH}	3.3	8	V	$\div P$	1
Control input low voltage	V_{INL}	0	1.7	V	$\div P +1$	1
Control input high current	V_{INH}		0.41	mA	$V_{INH} = 8V$	1
Control input low current	V_{INL}	-0.20		mA	$V_{INL} = 0V$	1
Clock to output delay	t_p		28	ns	$C_L = 10pF$	2
Set-up time	t_s	10		ns	$C_L = 10pF$	2
Release time	t_r	10		ns	$C_L = 10pF$	2

NOTES

1. Tested at $25^{\circ}C$ only
2. Guaranteed but not tested

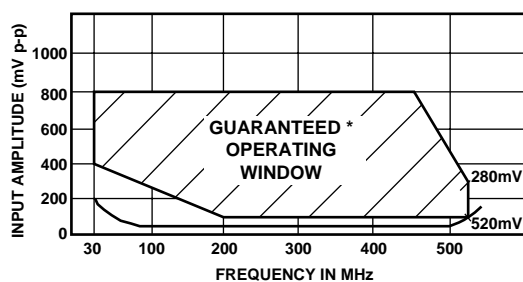


NOTE

The set-up time t_s is defined as the minimum time that can elapse between a $L \rightarrow H$ transition of the control input and the next $L \rightarrow H$ clock pulse transition to ensure that the $\div P$ mode is obtained.

The release time t_r is defined as the minimum time that can elapse between a $H \rightarrow L$ transition of the control input and the next $L \rightarrow H$ clock pulse transition to ensure that the $\div(P+1)$ mode is obtain

Figure 3 : Timing diagram



*Tested as specified in table of Electrical Characteristics

Figure 4 : Typical input characteristics

OPERATING NOTES

1. The inputs are biased internally and coupled to a signal source with suitable capacitors.
2. If no signal is present the devices will self-oscillate. If this is undesirable it may be prevented by connecting a 15k resistor from one input to pin 4 (ground). This will reduce the sensitivity.
3. The circuits will operate down to DC but slew rate must be better than 100V/ μ s.
4. The output stage is of an unusual design and is intended to interface with CMOS. External pull-up resistors or circuits must not be used.
5. This device is NOT suitable for driving TTL or its derivatives.

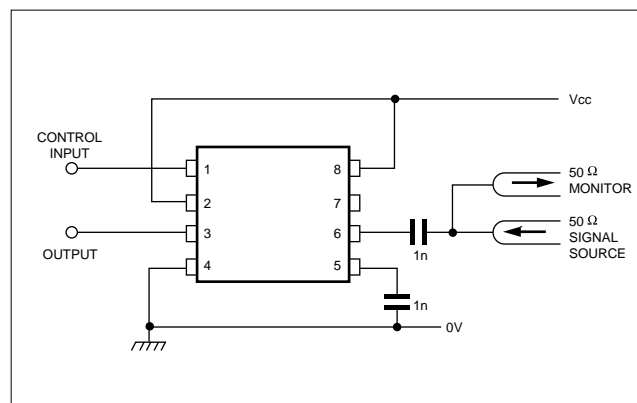


Figure 5: Toggle frequency test circuit

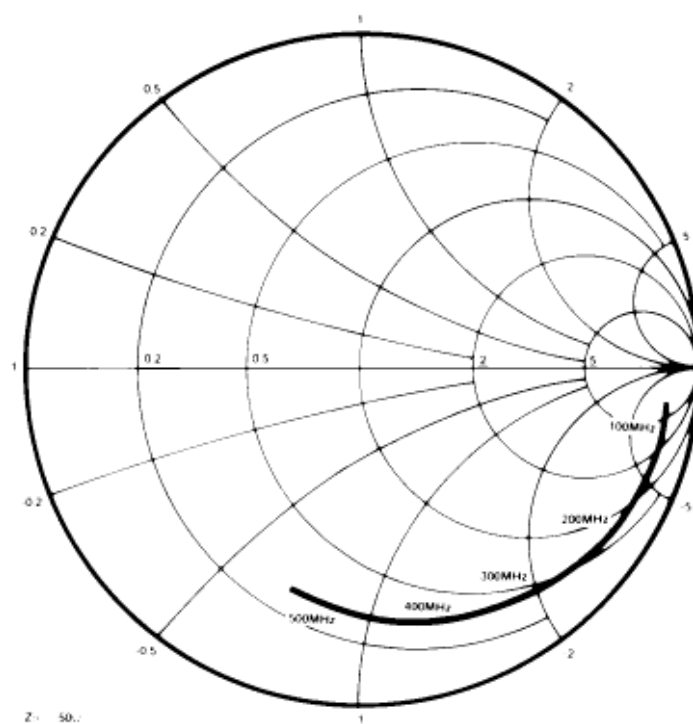


Figure 6 : Typical input impedance



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